

Problem 1

a) The Hamiltonian is only a function of \hat{S}_z , so \hat{H} and \hat{S}_z commute ($[\hat{H}, \hat{S}_z] = 0$). \hat{S}_x and \hat{S}_y do not commute with the Hamiltonian because $[\hat{S}_x, \hat{S}_z] \neq 0$ and $[\hat{S}_y, \hat{S}_z] \neq 0$.

b) The Hamiltonian has the same eigenstates as \hat{S}_z , so these are simply

- $|\uparrow\rangle$ (spin-up along the z-axis)
- $|\downarrow\rangle$ (spin-down along the z-axis)

The energy eigen value for the state $|\uparrow\rangle$ is

$$\hat{H}|\uparrow\rangle = -\gamma B_z \cdot +\frac{1}{2}\hbar |\uparrow\rangle, \text{ where we use } \hat{S}_z|\uparrow\rangle = +\frac{1}{2}\hbar |\uparrow\rangle$$

energy eigen value for $|\uparrow\rangle \Rightarrow E_{\uparrow} = +\frac{1}{2}\gamma\hbar B_z$

The energy eigen value for the state $|\downarrow\rangle$ is

$$H|\downarrow\rangle = -\gamma B_z \cdot -\frac{1}{2}\hbar |\downarrow\rangle, \text{ where we used } \hat{S}_z|\downarrow\rangle = -\frac{1}{2}\hbar |\downarrow\rangle$$

\Rightarrow the energy eigen value for $|\downarrow\rangle$ is

$$E_{\downarrow} = +\frac{1}{2}\gamma\hbar B_z$$

$E_{\uparrow} < E_{\downarrow}$, so $|\uparrow\rangle$ is the ground state and $|\downarrow\rangle$ the only excited state.

c) Resonant driving of quantum dynamics requires

$$\hbar f = E_{\downarrow} - E_{\uparrow} = \gamma\hbar B_z \Rightarrow f = \frac{\gamma B_z}{2\pi}$$

$$f = 27.11 \text{ MHz}$$

$$\hat{S}_z$$

$$\begin{aligned} \langle \uparrow | \hat{S}_z | \uparrow \rangle &= +\frac{1}{2}\hbar \\ \langle \downarrow | \hat{S}_z | \downarrow \rangle &= -\frac{1}{2}\hbar \\ \langle \uparrow | \hat{S}_z | \downarrow \rangle &= 0 \\ \langle \downarrow | \hat{S}_z | \uparrow \rangle &= 0 \end{aligned}$$

Further use the matrix representation in S_z basis

$$|\uparrow\rangle \leftrightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |\downarrow\rangle \leftrightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\hat{S}_x \leftrightarrow \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \hat{S}_y \leftrightarrow \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\hat{S}_x$$

$$\begin{aligned} \langle \uparrow | \hat{S}_x | \uparrow \rangle &= \frac{\hbar}{2} (10) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \\ \langle \downarrow | \hat{S}_x | \downarrow \rangle &= \frac{\hbar}{2} (01) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0 \end{aligned}$$

$$\langle \uparrow | \hat{S}_x | \downarrow \rangle = \frac{\hbar}{2} (10) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = +\frac{\hbar}{2}$$

$$\langle \downarrow | \hat{S}_x | \uparrow \rangle = \frac{\hbar}{2} (01) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = +\frac{\hbar}{2}$$

$$\hat{S}_y$$

$$\langle \uparrow | \hat{S}_y | \uparrow \rangle = \frac{\hbar}{2} (10) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0$$

$$\langle \downarrow | \hat{S}_y | \downarrow \rangle = \frac{\hbar}{2} (01) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0$$

$$\langle \uparrow | \hat{S}_y | \downarrow \rangle = \frac{\hbar}{2} (10) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = -i\frac{\hbar}{2}$$

$$\langle \downarrow | \hat{S}_y | \uparrow \rangle = \frac{\hbar}{2} (01) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = +i\frac{\hbar}{2}$$

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e) Define $\omega_p = \frac{E_p}{\hbar}$ and $\omega_d = \frac{E_d}{\hbar}$

$$|\psi(t)\rangle = e^{-i\omega_p t} \frac{1}{\sqrt{2}} \left(\sqrt{\frac{2}{3}} e^{-i\omega_p t} |\uparrow\rangle + i \sqrt{\frac{1}{3}} e^{-i\omega_p t} |\downarrow\rangle \right)$$

$$\langle \hat{S}_z \rangle(t) = \langle \psi(t) | \hat{S}_z | \psi(t) \rangle$$

$$= \left(\sqrt{\frac{2}{3}} e^{+i\omega_p t} \langle \uparrow | - i \sqrt{\frac{1}{3}} e^{+i\omega_p t} \langle \downarrow | \right) \hat{S}_z \left(\sqrt{\frac{2}{3}} e^{-i\omega_p t} |\uparrow\rangle + i \sqrt{\frac{1}{3}} e^{-i\omega_p t} |\downarrow\rangle \right)$$

$$= \frac{2}{3} \langle \uparrow | \hat{S}_z | \uparrow \rangle + \frac{1}{3} \langle \downarrow | \hat{S}_z | \downarrow \rangle$$

$$= +\frac{2}{3} \cdot \frac{1}{2} \hbar - \frac{1}{3} \cdot \frac{1}{2} \hbar = \frac{1}{6} \hbar$$

$$\langle \hat{S}_x \rangle(t) = \langle \psi(t) | \hat{S}_x | \psi(t) \rangle$$

$$= \left(\sqrt{\frac{2}{3}} e^{+i\omega_p t} \langle \uparrow | - i \sqrt{\frac{1}{3}} e^{+i\omega_p t} \langle \downarrow | \right) \hat{S}_x \left(\sqrt{\frac{2}{3}} e^{-i\omega_p t} |\uparrow\rangle + i \sqrt{\frac{1}{3}} e^{-i\omega_p t} |\downarrow\rangle \right)$$

$$= \frac{\sqrt{2}}{3} e^{-i(\omega_d - \omega_p)t} \cdot i \langle \uparrow | \hat{S}_x | \downarrow \rangle - \frac{\sqrt{2}}{3} e^{+i(\omega_d - \omega_p)t} \cdot i \langle \downarrow | \hat{S}_x | \uparrow \rangle$$

$$= \frac{\sqrt{2}}{3} i \frac{\hbar}{2} \left(e^{-i(\omega_d - \omega_p)t} - e^{+i(\omega_d - \omega_p)t} \right) = \frac{\sqrt{2}}{3} i \frac{\hbar}{2} (\cos - i \sin) - (\cos + i \sin)$$

$$= \frac{\sqrt{2}}{6} i (-i \sin(\omega_d - \omega_p)t - i \sin(\omega_d - \omega_p)t)$$

$$= \frac{\sqrt{2}}{3} \hbar \sin(\omega_d - \omega_p)t$$

4

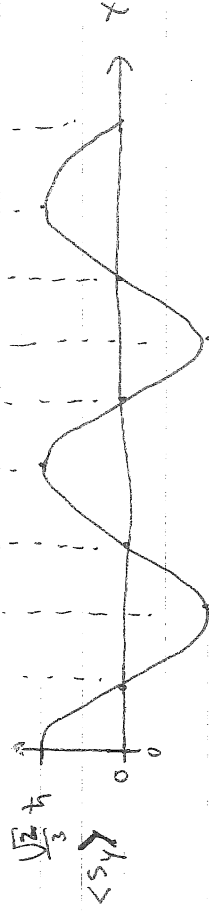
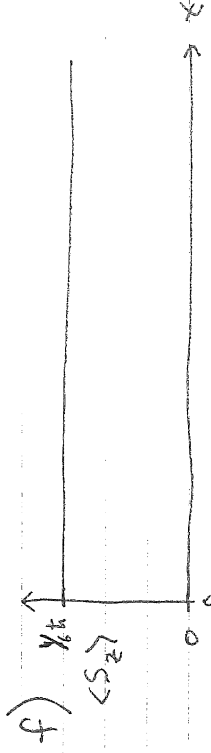
$$\langle S_y \rangle(t) = \langle \psi(t) | \hat{S}_y | \psi(t) \rangle$$

$$= \left(\sqrt{\frac{2}{3}} e^{+i\omega_p t} \langle \uparrow | - i \sqrt{\frac{1}{3}} e^{+i\omega_p t} \langle \downarrow | \right) \hat{S}_y \left(\sqrt{\frac{2}{3}} e^{-i\omega_p t} |\uparrow\rangle + i \sqrt{\frac{1}{3}} e^{-i\omega_p t} |\downarrow\rangle \right)$$

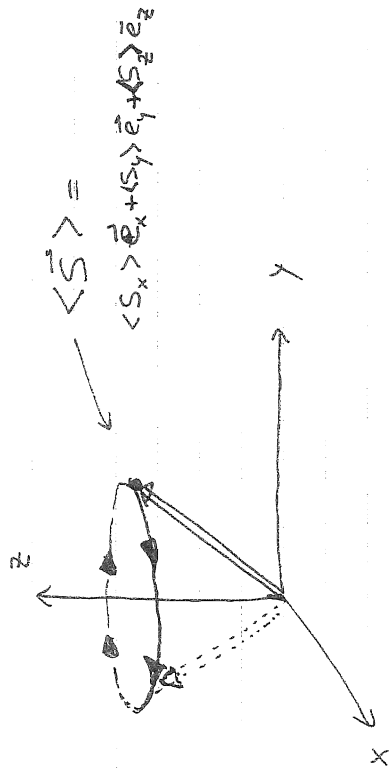
$$= \frac{\sqrt{2}}{3} e^{-i(\omega_d - \omega_p)t} \cdot i \langle \uparrow | \hat{S}_y | \downarrow \rangle - \frac{\sqrt{2}}{3} e^{+i(\omega_d - \omega_p)t} \cdot i \langle \downarrow | \hat{S}_y | \uparrow \rangle$$

$$= \frac{\sqrt{2}}{3} e^{-i(\omega_d - \omega_p)t} \cdot \frac{\hbar}{2} + \frac{\sqrt{2}}{3} e^{+i(\omega_d - \omega_p)t} \cdot \frac{\hbar}{2}$$

$$= \frac{\sqrt{2}}{3} \hbar \cos(\omega_d - \omega_p)t$$



The spin is precessing around the field $\vec{B} = B_z \cdot \vec{e}_z$ unit vector in z-direction



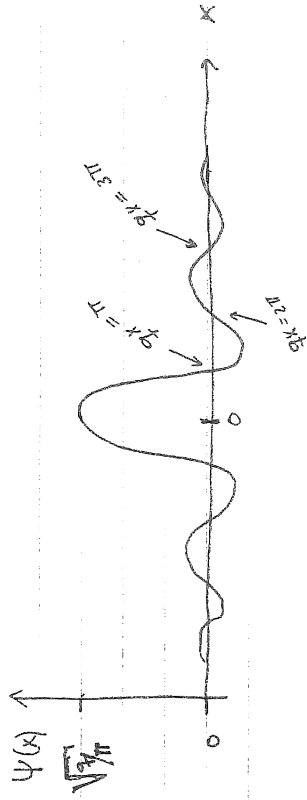
See also Griffiths book p. 181

g) Each spin has a magnetic moment $\vec{\mu} = \gamma \vec{S}$. So if the spins precess all together there is a rotating macroscopic magnetic moment (magnetization). You can measure that with a coil (electrical wire in loops). The oscillating magnetization induces a current (or electromagnetic force e.m.f) in the coil that you can detect (like the dynamo on your bike for getting electrical current in your bike lights).

①

Problem 2

$$\begin{aligned}
 \text{a) } \psi(x) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \Psi(k) e^{ikx} dk \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-q}^q \frac{1}{\sqrt{2q}} e^{ikx} dk = \frac{1}{\sqrt{4\pi q}} \left[\frac{1}{ix} e^{ikx} \right]_{-q}^q \\
 &= \frac{1}{\sqrt{4\pi q}} \left(\frac{1}{ix} e^{iqx} - \frac{1}{ix} e^{-iqx} \right) = \frac{1}{\sqrt{4\pi q}} \frac{2}{ix} (\sin(qx)) \\
 &= \sqrt{\frac{q}{\pi}} \frac{\sin(qx)}{qx} = \sqrt{\frac{q}{\pi}} \text{sinc}(qx)
 \end{aligned}$$

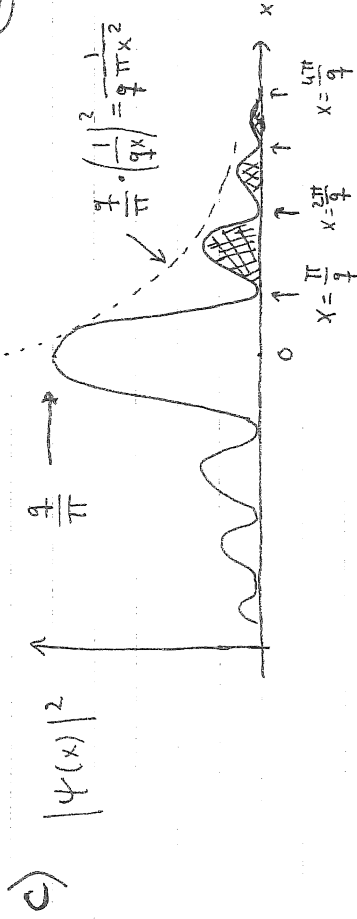


$$\text{b) } v_1 = 8000 \text{ m/s} \Rightarrow p_1 = m \cdot v_1 \Rightarrow k_1 = \frac{mv_1}{\hbar} = 0.8 \cdot 10^{10} \text{ m}^{-1}$$

$$v_2 = 10000 \text{ m/s} \Rightarrow p_2 = m v_2 \Rightarrow k_2 = \frac{mv_2}{\hbar} = 1.0 \cdot 10^{10} \text{ m}^{-1}$$

$$\begin{aligned}
 P(v_1 < v_2) &= \int_{k_1}^{k_2} |\Psi(k)|^2 dk = \int_{k_1}^{k_2} \frac{1}{2q} dk \\
 &= \frac{1}{2} (1 - 0.8) = 0.1
 \end{aligned}$$

2



$x_1 = 0.314 \text{ nm} \Rightarrow$ in the plot at $x = \frac{\pi}{4}$

$x_2 = 4 \times 0.314 \text{ nm} \Rightarrow$ in the plot at $x = \frac{4\pi}{4}$

So, the probability is the ~~xxx~~ area of the graph.

The main peak at $x=0$ has height $\frac{4}{\pi}$ (width is $\frac{2\pi}{9}$)

The peak at $x = \frac{3}{2} \frac{\pi}{4}$ has height $\frac{1}{9\pi} \frac{4}{4} \frac{\pi^2}{4} = \frac{1}{9\pi} \cdot \frac{4}{4} \cdot \frac{\pi^2}{4} \approx 0.04 \frac{1}{\pi}$
 \hookrightarrow width $\frac{\pi}{4}$

The peak at $x = \frac{5}{2} \frac{\pi}{4}$ has height $\frac{1}{9\pi} \cdot \frac{4}{25} \frac{\pi^2}{4} \approx 0.016 \frac{1}{\pi}$
 (ignore next small peak)

Area of these 2 peaks on the side

$\approx \frac{1}{2} * (0.04 + 0.016)$ fraction of the main peak

\Rightarrow Probability $\approx 2\%$

\uparrow
 Dominates
 the probability
 \Rightarrow area ≈ 1

d) After the measurement of X , $\Delta x \approx 0.001 \text{ nm}$ 3

$$\Rightarrow \Delta p_x \approx \frac{h}{2\Delta x} \Rightarrow \Delta k \approx \frac{1}{2\Delta x} \approx 5 \cdot 10^{11} \text{ m}^{-1}$$

$\Rightarrow \Delta k$ is about 50 times higher than for $\Psi_0(k)$.

\Rightarrow The value of $|\Psi(k)|^2$ is about 50 times lower.

So, the probability is about 50 times less than

for the answer on question b).

$$e) \quad \Psi(k, t) = e^{-\frac{i}{\hbar} H t} \Psi_0(k)$$

$$= e^{+\frac{i}{\hbar} \frac{\hbar^2 k^2}{2m} t} \Psi_0(k) \Rightarrow$$

$$\hat{H} = -\frac{\hbar^2 k^2}{2m}$$

\Rightarrow in k -representation
 $\xrightarrow{\text{simply}} \hat{H} \leftrightarrow -\frac{\hbar^2 k^2}{2m}$

$$\Psi(k, t) = \begin{cases} e^{+i\hbar \frac{\hbar^2 k^2}{2m} t} \frac{1}{\sqrt{2\pi}} & \text{for } |k| < q \\ 0 & \text{for all other } k \end{cases}$$

f) Besides the phase factors $e^{+i\hbar \frac{\hbar^2 k^2}{2m} t}$ the probability amplitudes for $\Psi(k)$ are not changing in time. So, the probabilities to measure v between v_1 and v_2 do not change as a function of time

g) The wave packet is spreading out in

space (becoming wider) both in the x direction

and the $-x$ direction. So, the probability

to find it in the interval between x_1 and x_2

goes down. The wave packet gets wider

at a speed that is about $v = \frac{\hbar g}{m}$.

4

1

Problem 3

a) $|\vec{J}_1| = \sqrt{\frac{63}{4}} \hbar = \sqrt{j_1(j_1+1)} \hbar \Rightarrow j_1 = \frac{7}{2}$

This is a half-integer value, so atom 1 is a fermion

$|\vec{J}_2| = \sqrt{2} \hbar = \sqrt{j_2(j_2+1)} \hbar \Rightarrow j_2 = 1$

This is an integer value, so atom 2 is a boson.

b) $\vec{J}_{tot} = \vec{J}_1 + \vec{J}_2 \Rightarrow$ follow rules for addition of angular momentum.

From a) we have $j_1 = \frac{7}{2}, j_2 = 1$. $|\vec{J}_{tot}|$ obeys

$$|\vec{J}_{tot}| |j_{tot}, m_{tot}\rangle = \sqrt{j_{tot}(j_{tot}+1)} \hbar |j_{tot}, m_{tot}\rangle$$

with $j_{tot} = |j_1 - j_2|, |j_1 - j_2| + 1, \dots, |j_1 + j_2| - 1, |j_1 + j_2|$

$$\Rightarrow j_{tot} = \frac{5}{2}, \frac{7}{2}, \frac{9}{2} \Rightarrow$$

Possible measurement outcomes are

$$\left\{ \begin{array}{l} |\vec{J}_{tot}| = \sqrt{\frac{7}{2}(\frac{7}{2})} \hbar = \sqrt{\frac{35}{4}} \hbar \\ |\vec{J}_{tot}| = \sqrt{\frac{7}{2}(\frac{9}{2})} \hbar = \sqrt{\frac{63}{4}} \hbar \\ |\vec{J}_{tot}| = \sqrt{\frac{9}{2}(\frac{11}{2})} \hbar = \sqrt{\frac{99}{4}} \hbar \end{array} \right.$$

c) The possible measurement outcomes for $J_{z,\text{tot}}$ and $J_{x,\text{tot}}$ are the same

if the starting point is that only $|J_{\text{tot}}\rangle$ is well defined.

The possible outcomes for J_z obey

$$J_z |j_{\text{tot}}, m_{\text{tot}}\rangle = m_{\text{tot}} \hbar |j_{\text{tot}}, m_{\text{tot}}\rangle$$

$$\text{with } m_{\text{tot}} = -j_{\text{tot}}, -(j_{\text{tot}}-1), \dots, +(j_{\text{tot}}-1), +j_{\text{tot}} \Rightarrow$$

Here all outcomes are covered by taking m_{tot} as

$$m_{\text{tot}} = -\frac{q}{2}, -\frac{q}{2} + \frac{\hbar}{2}, \dots, \frac{q}{2} - \frac{\hbar}{2}, \frac{q}{2} \Rightarrow$$

The possible outcomes for $J_{x,\text{tot}}$ and $J_{z,\text{tot}}$ are

$$-\frac{q}{2}\hbar, -\frac{q}{2}\hbar + \frac{\hbar}{2}, \dots, +\frac{q}{2}\hbar - \frac{\hbar}{2}, +\frac{q}{2}\hbar.$$